Virtual environment

Haptic device

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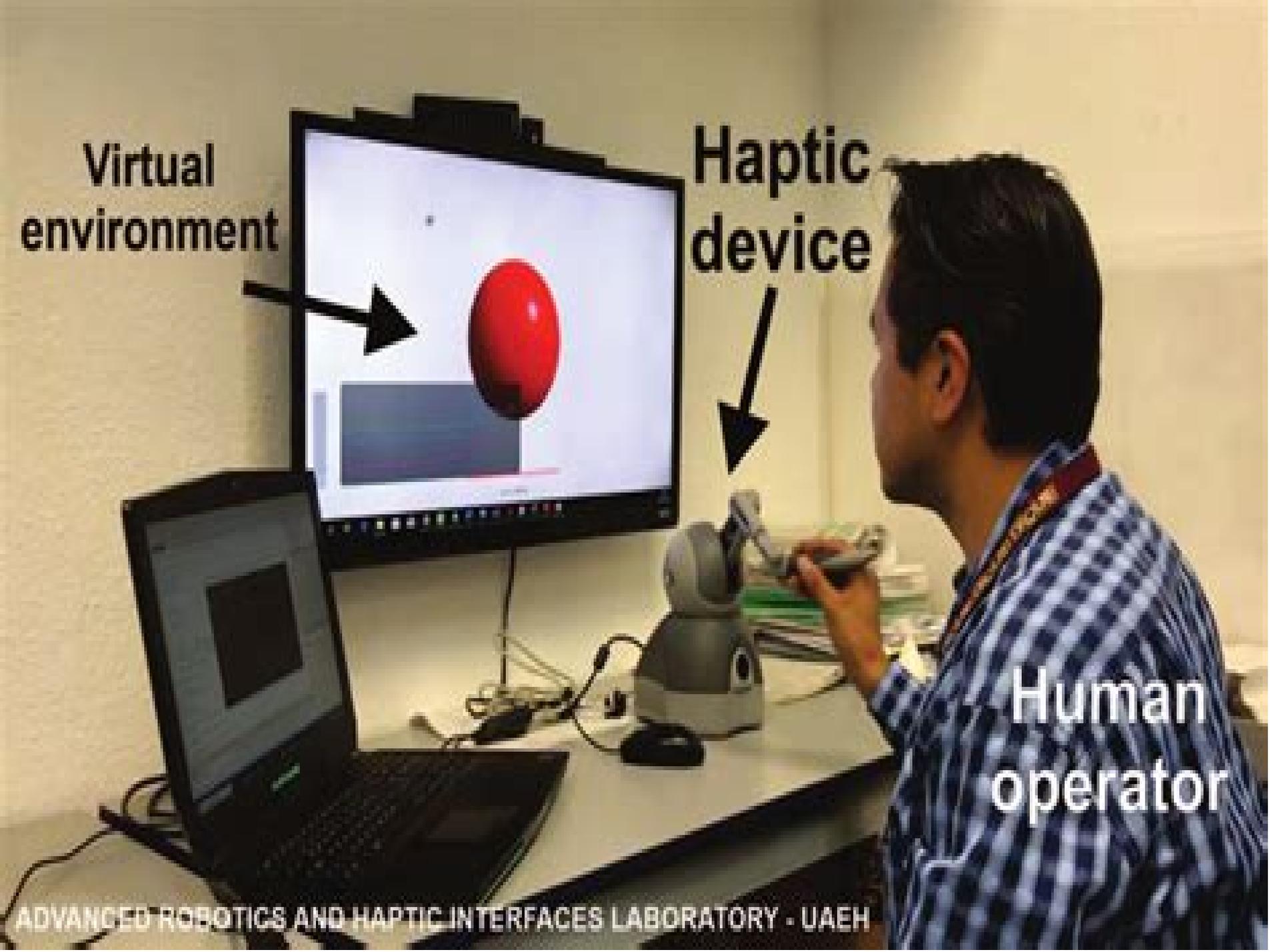
Haptic Interfaces For Virtual Environment And Teleoperator Systems Proceedings

Blake Hannaford,Janet M. Weisenberger,Brent Gillespie

Haptic Interfaces For Virtual Environment And Teleoperator Systems Proceedings:
     Haptic Interfaces for Virtual Environment and Teleoperator Systems, 2002. HAPTICS 2002. Proceedings. 10th Symposium on ,   Symposium on Haptic Interfaces for Virtual Environment and Teleoperator Systems 2006 Blake Hannaford,Janet M. Weisenberger,Brent Gillespie,2006   **Haptics 2003** ,2003   *Haptic Interfaces for Virtual Environment and Teleoperator Systems, 2004. HAPTICS '04. Proceedings. 12th International Symposium on* IEEE Computer Society Staff,2004   HAPTICS 2004 ,2004   *Proceedings First Joint Eurohaptics Conference, and Symposium on Haptic Interfaces for Virtual Environment and Teleoperator Systems* ,2005   *The Synthesis of Three Dimensional Haptic Textures: Geometry, Control, and Psychophysics* Gianni Campion,2011-05-16 The sense of touch is fundamental during the interaction between humans and their environment in virtual reality objects are created by computer simulations and they can be experienced through haptic devices In this context haptic textures are fundamental for a realistic haptic perception of virtual objects This book formalizes the specific artefacts corrupting the rendering of virtual haptic textures and offers a set of simple conditions to guide haptic researchers towards artefact free textures The conditions identified are also extremely valuable when designing psychophysical experiments and when analyzing the significance of the data collected The Synthesis of Three Dimensional Haptic Textures Geometry Control and Psychophysics examines the problem of rendering virtual haptic textures with force feedback devices The author provides an introduction to the topic of haptic textures that covers the basics of the physiology of the skin the psychophysics of roughness perception and the engineering challenges behind haptic textures rendering The book continues with the presentation of a novel mathematical framework that characterizes haptic devices texturing algorithms and their ability to generate realistic haptic textures Finally two psychophysical experiments link the perception of roughness with the parameters of the haptic rendering algorithms This book formalizes the specific artefacts corrupting the rendering of virtual haptic textures and offers a set of simple conditions to guide haptic researchers towards artefact free textures The conditions identified are also extremely valuable when designing psychophysical experiments and when analyzing the significance of the data collected   *Performance Metrics for Haptic Interfaces* Evren Samur,2012-07-13 Haptics technology is being used more and more in different applications such as in computer games for increased immersion in surgical simulators to create a realistic environment for training of surgeons in surgical robotics due to safety issues and in mobile phones to provide feedback from user action The existence of these applications highlights a clear need to understand performance metrics for haptic interfaces and their implications on device design use and application Performance Metrics for Haptic Interfaces aims at meeting this need by establishing standard practices for the evaluation of haptic interfaces and by identifying significant performance metrics Towards this end a combined physical and psychophysical experimental methodology is presented Firstly existing physical performance measures and device characterization techniques are investigated and described in an illustrative way Secondly a wide range of human

psychophysical experiments are reviewed and the appropriate ones are applied to haptic interactions The psychophysical experiments are unified as a systematic and complete evaluation method for haptic interfaces Finally synthesis of both evaluation methods is discussed The metrics provided in this state of the art volume will guide readers in evaluating the performance of any haptic interface The generic methodology will enable researchers to experimentally assess the suitability of a haptic interface for a specific purpose to characterize and compare devices quantitatively and to identify possible improvement strategies in the design of a system   Haptics for Virtual Reality and Teleoperation Matjaž Mihelj,Janez Podobnik,2012-12-14 This book covers all topics relevant for the design of haptic interfaces and teleoperation systems The book provides the basic knowledge required for understanding more complex approaches and more importantly it introduces all issues that must be considered for designing efficient and safe haptic interfaces Topics covered in this book provide insight into all relevant components of a haptic system The reader is guided from understanding the virtual reality concept to the final goal of being able to design haptic interfaces for specific tasks such as nanomanipulation The introduction chapter positions the haptic interfaces within the virtual reality context In order to design haptic interfaces that will comply with human capabilities at least basic understanding of human sensors motor system is required An overview of this topic is provided in the chapter related to human haptics The book does not try to introduce the state of the art haptic interface solutions because these tend to change quickly Only a careful selection of different kinematic configurations is shown to introduce the reader into this field Mathematical models of virtual environment collision detection and force rendering topics are strongly interrelated and are described in the next two chapters The interaction with the virtual environment is simulated with a haptic interface Impedance and admittance based approaches to haptic robot control are presented Stability issues of haptic interaction are analyzed in details and solutions are proposed for guaranteeing stable and safe operation Finally haptic interaction is extended to teleoperation systems Virtual fixtures which improve the teleoperation and human robot cooperation in complex environments are covered next and the last chapter presents nanomanipulation as one specific example of teleoperation   *Symposium on Haptics Interfaces for Virtual Environment and Teleoperator Systems 2008* Janet M. Weisenberger,Allison Okamura,Karon MacLean,2008   **Proceedings of the ASME Dynamic Systems and Control Division** American Society of Mechanical Engineers. Dynamic Systems and Control Division,1997-01-01 One hundred plus papers from symposia at the November 1997 meeting discuss haptic interfaces for virtual environment and teleoperator systems expert and intelligent systems design and control of smart machines intelligent sensors and instrumentation biomechanics robotics robust nonlinear contr   **Human Haptic Perception** Martin Grunwald,2008-12-10 Haptic perception human beings active sense of touch is the most complex of human sensory systems and has taken on growing importance within varied scientific disciplines as well as in practical industrial fields This book s international team of authors presents the most comprehensive collection of writings on the subject published to date and cover the results of

research as well as practical applications After an introduction to the theory and history of the field subsequent chapters are dedicated to the neuro physiological basics as well as the psychological and clinical neuro psychological aspects of haptic perception   **Proceedings of the ASME Dynamic Systems and Control Division** ,1998   *The Human-Computer Interaction Handbook* Andrew Sears,Julie A. Jacko,2002-09-01 The Human Computer Interaction Handbook Fundamentals Evolving Technologies and Emerging Applications is a comprehensive survey of this fast paced field that is of interest to all HCI practitioners educators consultants and researchers This includes computer scientists industrial electrical and computer engineers cognitive scientists exp   *Enhancing Performance for Action and Perception* ,2011-07-16 This volume of Progess in Brain Research follows on from the 32nd International Symposium of the Groupe de recherche sur le syst me nerveux central GRSNC May 2010 and aims to provide an overview of the various neural mechanisms that contribute to learning new motor and sensory skills and to adapting to changed circumstances including the use of devices and implants to substitute for lost sensory or motor abilities brain machine interfaces The focus is on recent developments covering five major themes Mechanisms to improve motor performance Neuro rehabilitation of motor function Mechanisms to enhance sensory perception Cross modal interationc for enhancing sensorimotor performance Assistive technologies to enhance sensorimotor performance This volume focuses on the translation of scientific knowledge into applications and strategies that can help restore lost function following injury or disease including assistive neuroprosthetic technologies to enhance sensorimotor performance and neurorehabilitation Leading authors review the state of the art in their field of investigation and provide their views and perspectives for future research Chapters are extensively referenced to provide readers with a comprehensive list of resources on the topics covered All chapters include comprehensive background information and are written in a clear form that is also accessible to the non specialist   **Emboding Intelligence in Structures and Integrated Systems** Pietro Vincenzini,Fabio Casciati,2008-09-02 CIMTEC 2008 Selected peer reviewed papers from the Symposium C Emboding Intelligence in Structures and Integrated Systems of CIMTEC 2008 3rd International Conference Smart Materials Structures and Systems held in Acireale Sicily Italy June 8 13 2008   **Human Computer Interaction Handbook** Julie A. Jacko,2012-05-04 Winner of a 2013 CHOICE Outstanding Academic Title Award The third edition of a groundbreaking reference The Human Computer Interaction Handbook Fundamentals Evolving Technologies and Emerging Applications raises the bar for handbooks in this field It is the largest most complete compilation of HCI theories principles advances case st   **10th International Symposium on Haptic Interfaces for Virtual Environment and Teleoperator Systems** ,2002 This volume originates from the 10th International Symposium on Haptic Interfaces for Virtual Environment and Teleoperator Systems and examines computer graphics It is aimed at researchers professors practitioners and students   *Haptic Visualization* Doanna M. Weissgerber,2004   *CHI ... Conference Proceedings* ,2006

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